

Amendments to the Specification:

Please replace the paragraph in lines 5-13 of page 9 with the following paragraph:

In order to apply tape with as much precision as possible, it is very beneficial to cut the tape while the head remains in contact with the body part so that the tape which has been applied will not be pulled away from the body part. In the preferred embodiment, as illustrated in FIG. 3, a knife blade (17) is provided which is located within the perimeter or external profile of the tape applicator head. More specifically, the knife blade (17) is provided within the perimeter or external profile of the nose (9), as also illustrated in FIG. 3. For certain body parts, it is necessary for the tape applicator head to move within a fairly narrow or confined space, so a small nose on the tape applicator head is beneficial. By incorporating the blade into the nose so that it does not protrude when the tape is in motion, the best results are achieved.

Please replace the first paragraph in lines 1-8 of page 11, with the following paragraph:

The shape of the nose can affect the efficiency of tape application. As shown in Figure 3, a [A] smooth radius at the tip of the non-rotary nose (9) (thus, the smooth radius is non-rotary as well) prevents excess tension in the tape (3). If the centre point (35) of the radius of the nose tip (as shown in Figure 3) is in line with the roll axis (14) of the robot arm (as shown in Figure 3) is in line with the roll axis (14) of the robot arm (as shown in Figures 1 and 2), optimum results appear to be obtained. The roll axis of the robot is the tool point around which the robot rotates. When the centre point of the radius at the tip of the nose is in line with the roll axis of the robot, it is possible to take advantage of the circular programming functions of the robot to create extremely smooth arcing motions.